A Characterization of Deterministic Sampling Patterns for Low-Rank Matrix Completion

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Allerton, 2015

Outline

- Introduction
- When can we Low-Rank Matrix Complete?
- The Answer
- Implications
- Idea of the proof
- Conclusions
- Open questions (if time allows)

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- When can we Low-Rank Matrix Complete?
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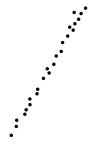


And we want to analyze it.

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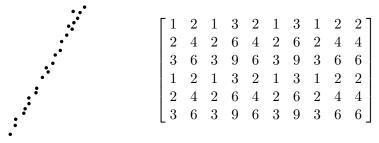
Because data is often well-modeled by linear subspaces.



[1	2	1	3	2	1	3	1	2	2]
2	4	2	6	4	2	6	2	4	4
3	6	3	9	6	3	9	3	6	6
1	2	1	3	2	1	3	1	2	2
2	4	2	6	4	2	6	2	4	4
3	6	3	9	6	3	9	3	6	$\begin{bmatrix} 2\\4\\6\\2\\4\\6\end{bmatrix}$

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▶ We know how to find the subspace (e.g., using SVD).

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• Example: Vision.



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• We still want to find subspaces.

Low-Rank Matrix Completion (LRMC) aims to find the subspace from incomplete datasets.

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$$S^{\star} = \operatorname{span} \begin{bmatrix} 1\\1\\1\\1\\1 \end{bmatrix}.$$

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- Then with high probability you can complete the matrix.

But what if these assumptions are not met?

What makes a matrix completable?

- What makes a matrix completable?
- What conditions must a matrix satisfy?

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Setup

• For any matrix Ω' formed with a subset of the columns in Ω :

$$\Omega' = \underbrace{\begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}}_{n(\Omega') := \# \text{columns}} \Biggr\} m(\Omega') := \# \text{nonzero rows}$$

Theorem (P.-A., Nowak, Boston (Allerton '15))

For almost every \mathbf{X} , there exist at most finitely many rank-r completions of \mathbf{X}_{Ω} if and only if every matrix Ω' formed with a subset of the columns in Ω satisfies

$$m(\mathbf{\Omega}') \geq n(\mathbf{\Omega}')/r + r.$$

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$$\mathbf{X}_{\mathbf{\Omega}} = \begin{bmatrix} 1 & 1 & 3 & \cdot \\ 1 & 2 & \cdot & 1 \\ 3 & \cdot & 5 & 4 \\ \cdot & 7 & 6 & 5 \end{bmatrix}$$

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$$\mathbf{X}_{\Omega} = \begin{bmatrix} 1 & 1 & 3 & \cdot \\ 1 & 2 & \cdot & 1 \\ 3 & \cdot & 5 & 4 \\ \cdot & 7 & 6 & 5 \end{bmatrix} \qquad \qquad \Rightarrow \begin{cases} \mathbf{X} = \begin{bmatrix} 1 & 1 & 3 & 2 \\ 1 & 2 & 1 & 1 \\ 3 & 5 & 5 & 4 \\ 4 & 7 & 6 & 5 \end{bmatrix} \\ \mathbf{X} = \begin{bmatrix} 1 & 1 & 3 & 10 \\ 1 & 2 & \frac{21}{13} & 1 \\ \frac{3 & \frac{53}{9} & 5 & 4}{\frac{68}{19} & 7 & 6 & 5} \end{bmatrix}$$

For almost every X, there exist at most finitely many rank-r completions of X_Ω if and only if every matrix Ω' formed with a subset of the columns in Ω satisfies

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The answer

Now we know when there are at most finitely many completions.

► Then what?

Theorem (P.-A., Nowak, Boston (Allerton '15))

If in addition X_{Ω} has an extra (d-r) columns observed on $\hat{\Omega}$, such that every matrix Ω' formed with a subset of the columns in $\hat{\Omega}$ satisfies

$$m(\mathbf{\Omega}') \geq n(\mathbf{\Omega}') + r,$$

then X can be uniquely recovered from X_{Ω} .

If a matrix does not satisfy our sampling conditions, then you cannot complete it.

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Sometimes finitely completable = uniquely completable (e.g., rank=1), but sometimes not.

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$$\mathbf{X}_{\mathbf{\Omega}} = \begin{bmatrix} 1 & 1 & 3 & \cdot & -1 & 1 \\ 1 & 2 & \cdot & 1 & \cdot & -1 \\ 3 & \cdot & 5 & 4 & 3 & \cdot \\ \cdot & 7 & 6 & 5 & 5 & -2 \end{bmatrix}$$

The Answer (take home message)

In essence:

r complete columns (linearly independent) uniquely define an r-dimensional subspace.

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r **complete** columns (linearly independent) uniquely define an r-dimensional subspace.

(r+1)(d-r) incomplete columns (observed in the right places) uniquely define an $r\mbox{-dimensional subspace}.$

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Implications (coherence)

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 - ► For almost every matrix, O(max{r, log d}) uniform random entries per column are sufficient for completion.
- Regardless of coherence!

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- Help answer an important open question:
 - The Sample Complexity of Subspace Clustering with Missing Data.

Validation criteria:

Suppose you observe the right entries.

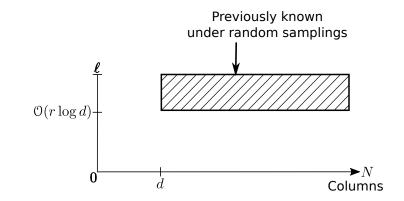
- Suppose you observe the right entries.
- Try to complete the matrix using any method.

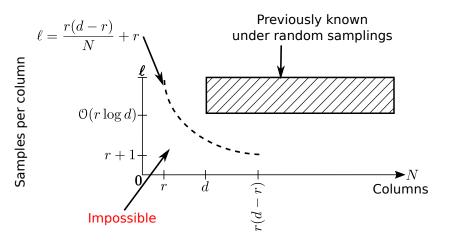
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- ▶ If you find a rank-*r* completion, then it is the right completion.

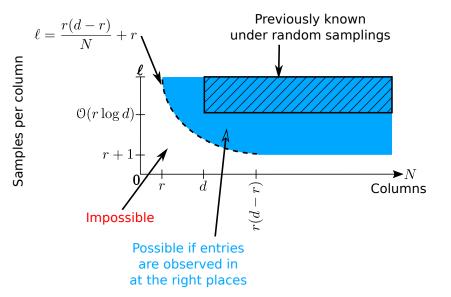
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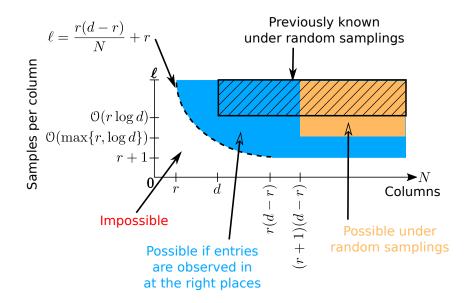
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- With probability 1 (as opposed to *with high probability*).







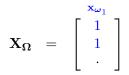


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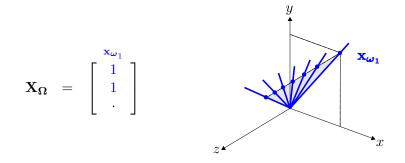
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A column with r + 1 samples imposes one restriction on what the subspace may be.

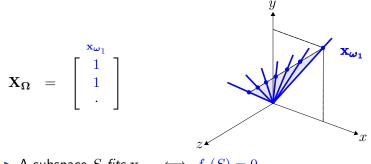
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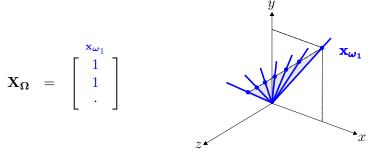


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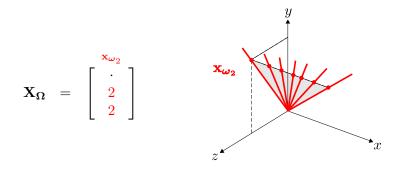
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This reduces one degree of freedom in the Grassmannian.

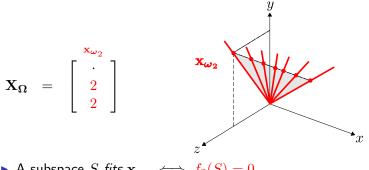
An other column with r + 1 samples imposes an other restriction.

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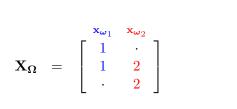


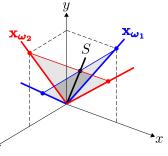
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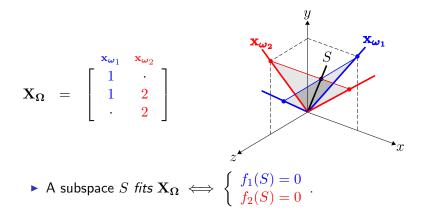


• A subspace S fits $\mathbf{x}_{\boldsymbol{\omega}_2} \iff f_2(S) = 0$.

$$\mathbf{X}_{\boldsymbol{\Omega}} \hspace{0.1 cm} = \hspace{0.1 cm} \begin{bmatrix} \mathbf{x}_{\boldsymbol{\omega}_{1}} & \mathbf{x}_{\boldsymbol{\omega}_{2}} \\ 1 & \cdot \\ 1 & 2 \\ \cdot & 2 \end{bmatrix}$$







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- The Grassmannian has r(d-r) degrees of freedom.
- If we have r(d-r) not redundant restrictions:
 - We can identify S^{\star} up to finite choice.

f_i(S) only involves the variables (of *S*) corresponding to the nonzero rows of *ω_i*.

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- ► We want all sets of *n* polynomials to involve at least *n*/*r* + *r* variables (otherwise they will be dependent)

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This sheds new light on LRMC.

Thanks.

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- Open questions

It is one thing to be theoretically able to complete a matrix; an other one to complete it efficiently.

▶ P.-A., Nowak, Boston (Allerton '15):

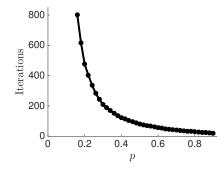
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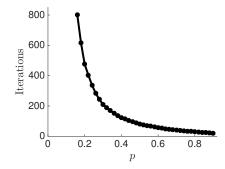
- P.-A., Nowak, Boston (Allerton '15):
 - New sampling regimes where you can theoretically complete a matrix.
 - This may involve solving a complex system of polynomial equations!
 - This is computationally prohibitive.

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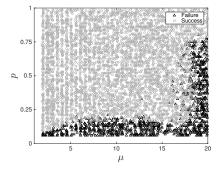
Does missingness come at a price?



How much missing data can we handle and remain computationally efficient?

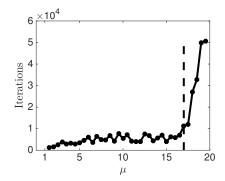
Can practical algorithms complete coherent matrices?

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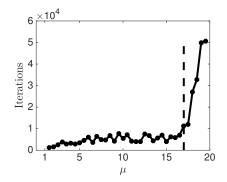


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How much coherence can we handle and remain computationally efficient?

Thanks again!

Thanks again! (this time I'm really done)