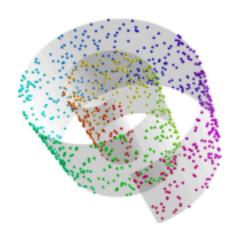
Low Algebraic Dimension Matrix Completion



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JSM

Joint work with:



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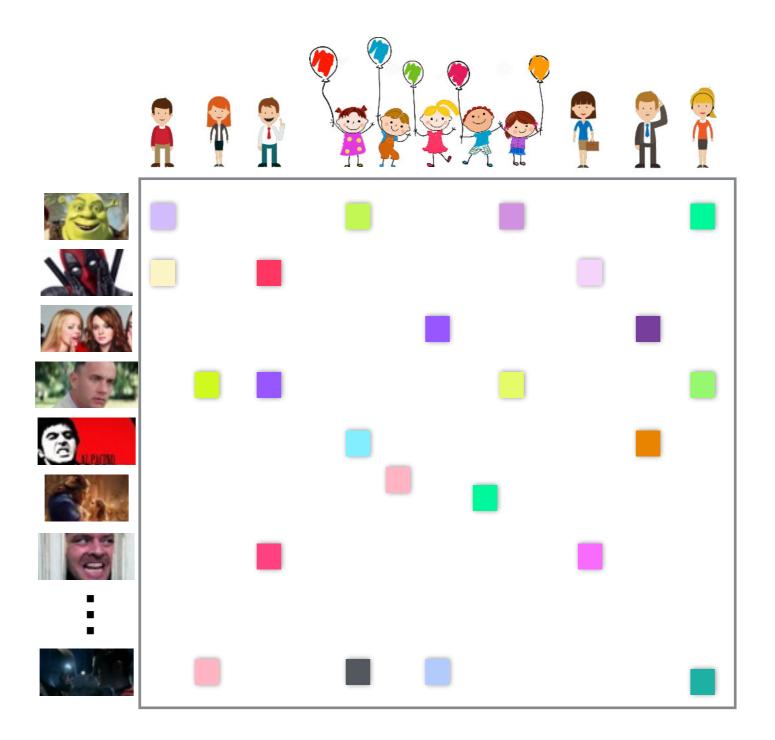


Laura Balzano



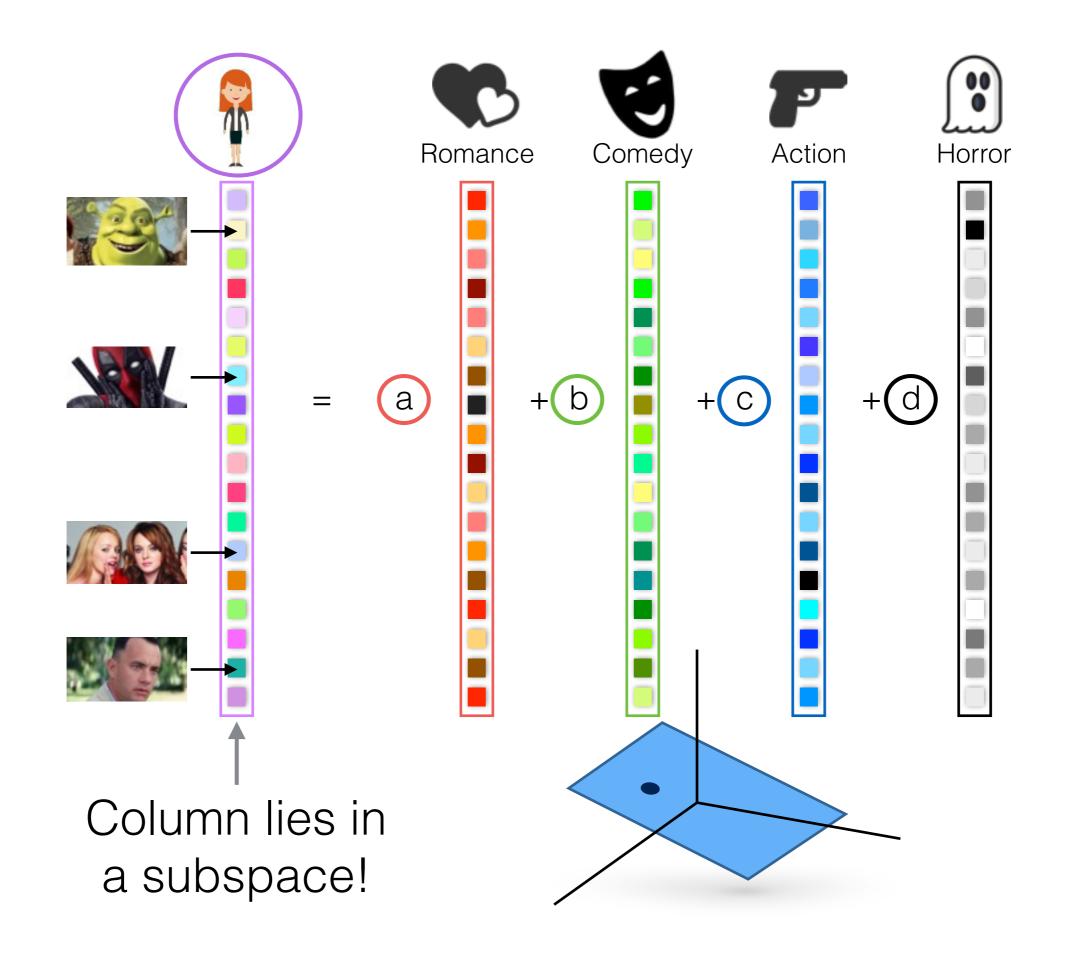
Becca Willett Rob Nowak University of Wisconsin-Madison

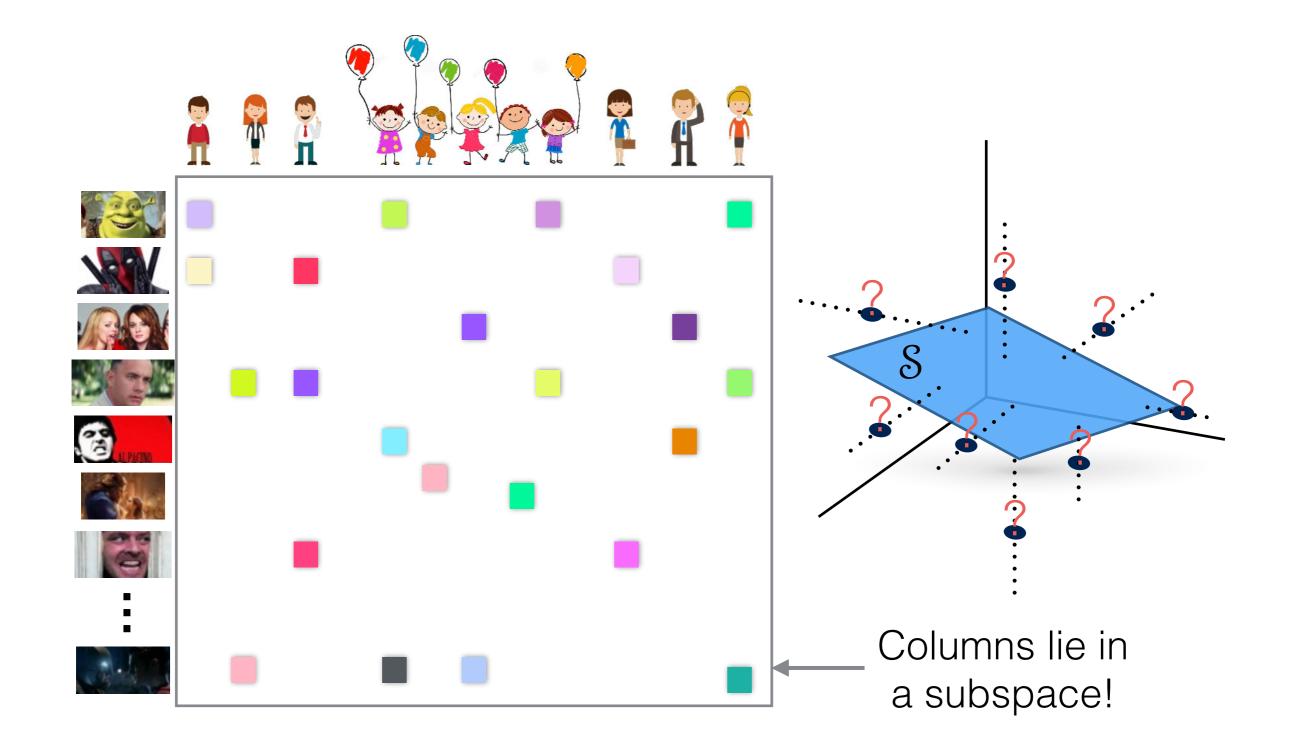




Textbook Example

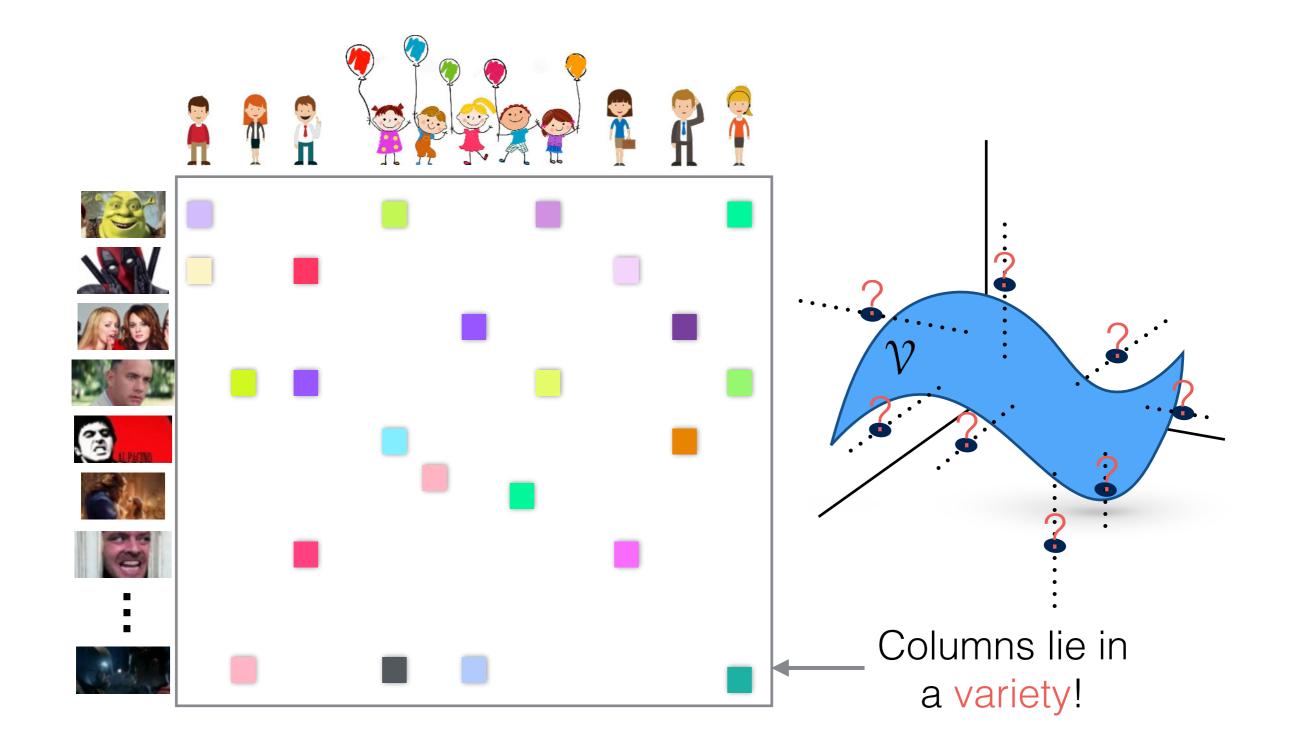
Recommender Systems





We want to find this Subspace!

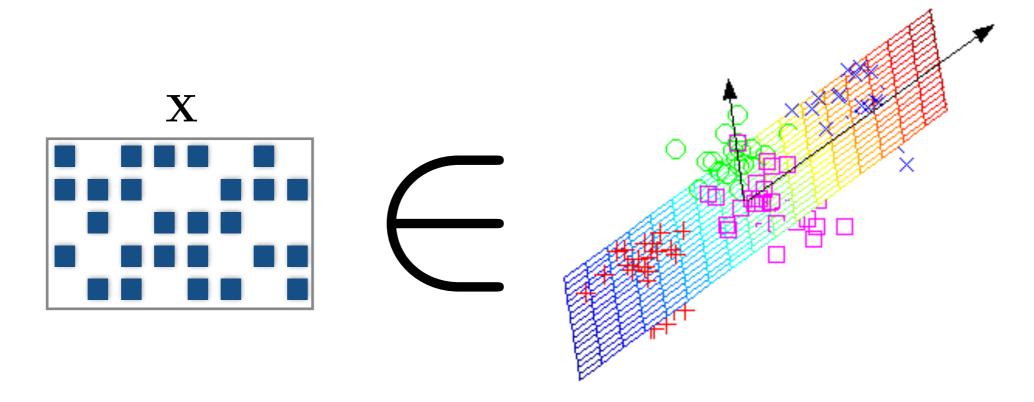
Problem is: data is incomplete!



What if dependencies are nonlinear?!

Problem is: data is incomplete!

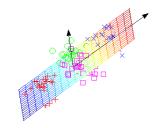
What am I telling you?

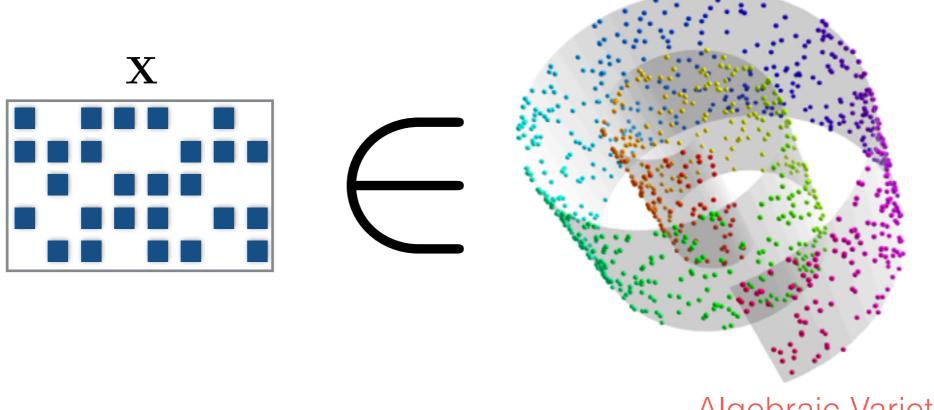


Given: Incomplete data matrix

Goal: Find linear subspace that explains data

Low-Rank Matrix Completion



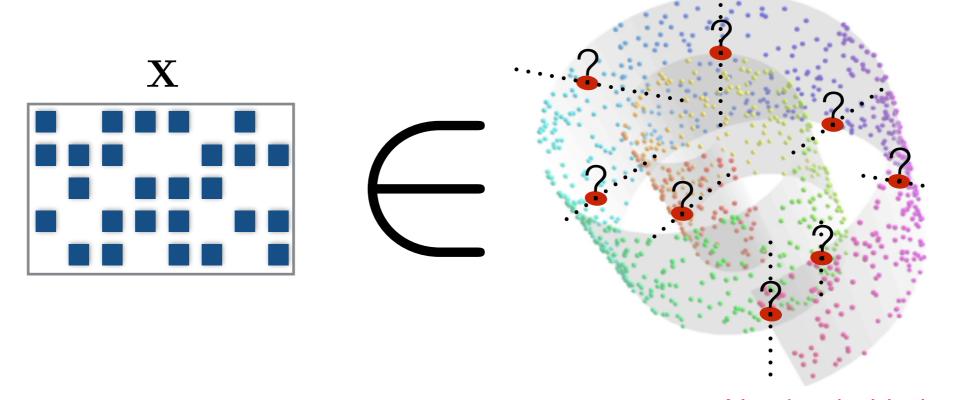


Given: Incomplete data matrix

Algebraic Variety
Goal: Find linear subspace
that explains data

Low Rank Matrix Completion

Low Algebraic Dimension

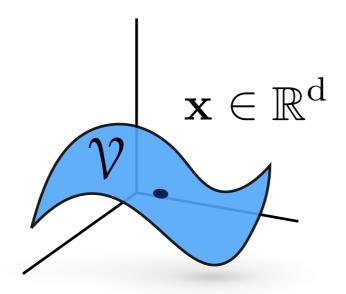


Given: Incomplete data matrix

Algebraic Variety
Goal: Find linear subspace
that explains data

Is it possible? Yes When you observe the right entries How? Using tensors





$$\begin{cases} f_1(\mathbf{x}) = 0 \\ f_2(\mathbf{x}) = 0 \\ \vdots \\ f_N(\mathbf{x}) = 0 \end{cases}$$

Consider a point in a variety

$$\mathbf{x} \in \mathbb{R}^d$$

$$\begin{array}{l} \left(\begin{array}{l} v_{11}x_{1}^{2} + v_{12}x_{1}x_{2} + v_{13}x_{1}x_{3} + \cdots + v_{1D}x_{d}^{2} \ = \ 0 \\ \\ v_{21}x_{1}^{2} + v_{22}x_{1}x_{2} + v_{23}x_{1}x_{3} + \cdots + v_{2D}x_{d}^{2} \ = \ 0 \\ \\ \vdots \\ \\ v_{N1}x_{1}^{2} + v_{N2}x_{1}x_{2} + v_{N3}x_{1}x_{3} + \cdots + v_{ND}x_{d}^{2} \ = \ 0 \end{array} \right)$$

Consider a point in a variety

$$\mathbf{x} \in \mathcal{V}$$

$$\mathbf{X} \in \mathbf{7}$$

$$\mathbf{v}_{11}x_1^2 + \mathbf{v}_{12}x_1x_2 + \mathbf{v}_{13}x_1x_3 + \dots + \mathbf{v}_{1D}x_d^2 = 0$$

$$\mathbf{X} \in \mathbf{\widehat{V}} \quad \begin{cases} \mathbf{v}_{11} \mathbf{x}_{1}^{2} + \mathbf{v}_{12} \mathbf{x}_{1} \mathbf{x}_{2} + \mathbf{v}_{13} \mathbf{x}_{1} \mathbf{x}_{3} + \dots + \mathbf{v}_{1D} \mathbf{x}_{d}^{2} = 0 \\ \mathbf{v}_{21} \mathbf{x}_{1}^{2} + \mathbf{v}_{22} \mathbf{x}_{1} \mathbf{x}_{2} + \mathbf{v}_{23} \mathbf{x}_{1} \mathbf{x}_{3} + \dots + \mathbf{v}_{2D} \mathbf{x}_{d}^{2} = 0 \end{cases}$$

$$\mathbf{X} \in \bigvee^{\mathbf{v}_{11}x_{1}^{2} + \mathbf{v}_{12}x_{1}x_{2} + \mathbf{v}_{13}x_{1}x_{3} + \dots + \mathbf{v}_{1D}x_{d}^{2}} = 0$$

$$\mathbf{v}_{21}x_{1}^{2} + \mathbf{v}_{22}x_{1}x_{2} + \mathbf{v}_{23}x_{1}x_{3} + \dots + \mathbf{v}_{2D}x_{d}^{2}} = 0$$

$$\vdots$$

$$\mathbf{v}_{N1}x_{1}^{2} + \mathbf{v}_{N2}x_{1}x_{2} + \mathbf{v}_{N3}x_{1}x_{3} + \dots + \mathbf{v}_{ND}x_{d}^{2}} = 0$$

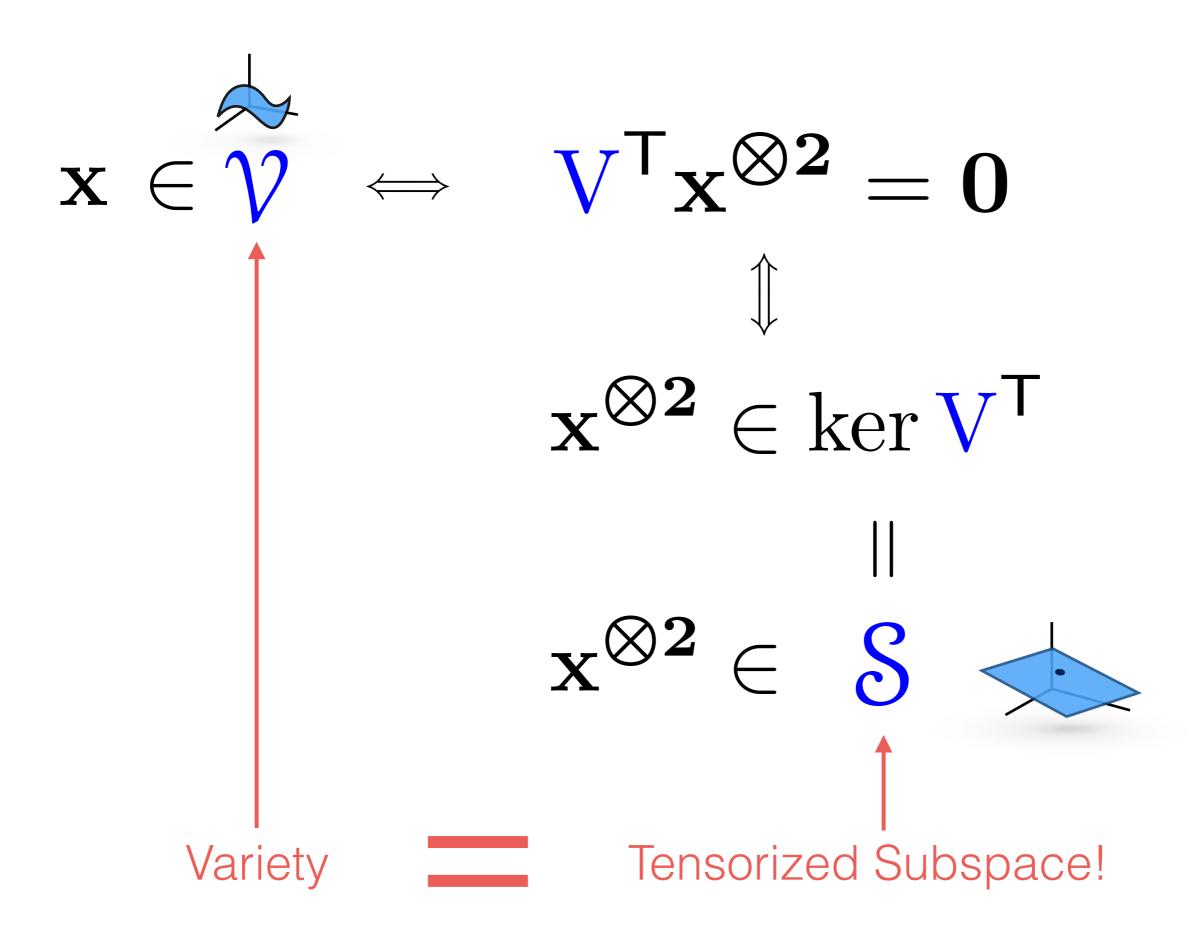
$$\begin{bmatrix} v_{11} & v_{12} & v_{13} & \cdots & v_{1D} \\ v_{21} & v_{22} & v_{23} & \cdots & v_{2D} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ v_{N1} & v_{N2} & v_{N3} & \cdots & v_{ND} \end{bmatrix} \begin{bmatrix} x_1^2 \\ x_1x_2 \\ x_1x_3 \\ \vdots \\ x_d^2 \end{bmatrix} = \mathbf{0}$$

$$\mathbf{X} \in \bigvee^{v_{11}x_{1}^{2} + v_{12}x_{1}x_{2} + v_{13}x_{1}x_{3} + \dots + v_{1D}x_{d}^{2}} = 0$$

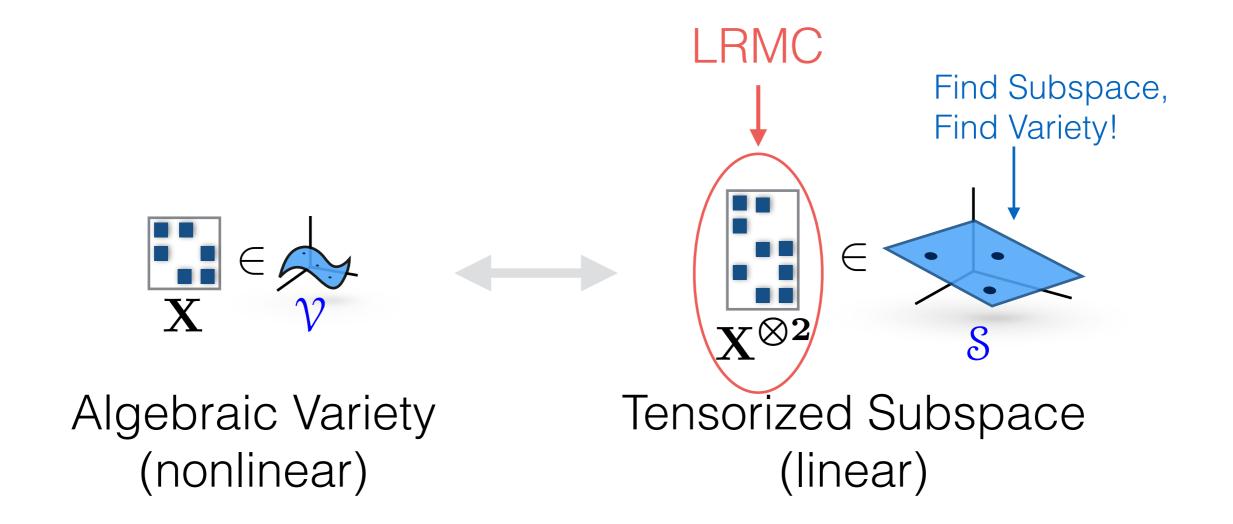
$$v_{21}x_{1}^{2} + v_{22}x_{1}x_{2} + v_{23}x_{1}x_{3} + \dots + v_{2D}x_{d}^{2} = 0$$

$$\vdots$$

$$v_{N1}x_{1}^{2} + v_{N2}x_{1}x_{2} + v_{N3}x_{1}x_{3} + \dots + v_{ND}x_{d}^{2} = 0$$



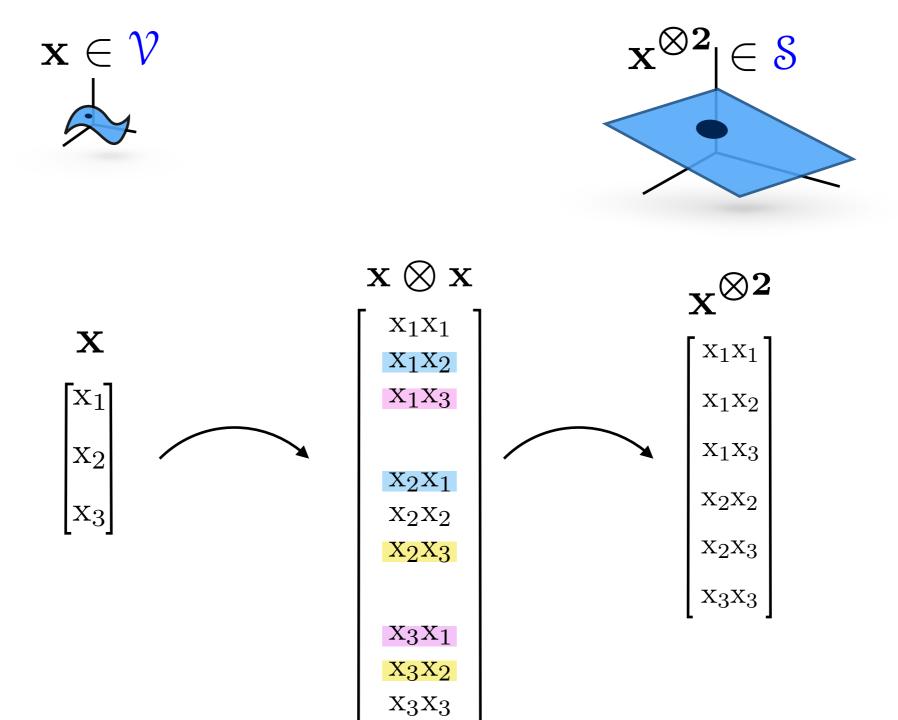
What does this mean?



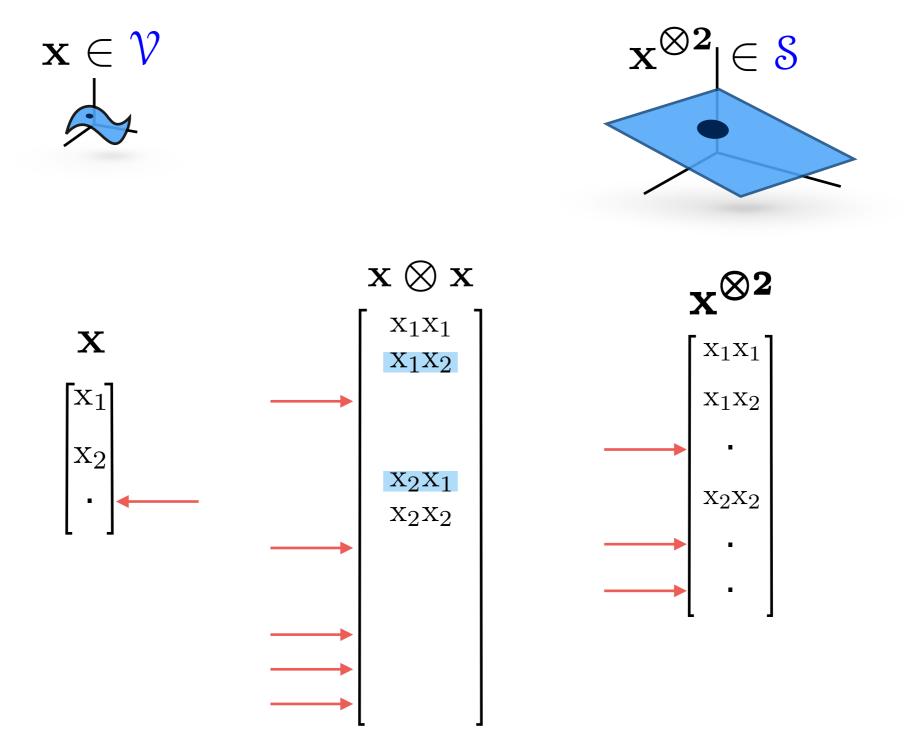
What does this mean?

Is this just standard Low-Rank Matrix Completion?

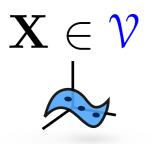
More or less...

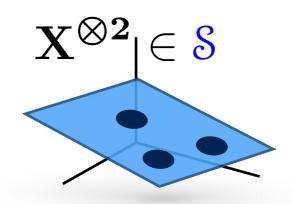


Recall...



The sampling is highly restricted!





 \mathbf{X}

$$\begin{bmatrix} x_1 & x_1 & \cdot \\ x_2 & \cdot & x_2 \\ \cdot & x_3 & x_3 \end{bmatrix}$$

 $\mathbf{X}^{\otimes \mathbf{2}}$

$$\begin{bmatrix} x_1^2 & x_1^2 & \cdot \\ x_1x_2 & \cdot & \cdot \\ \cdot & x_1x_3 & \cdot \\ x_2^2 & \cdot & x_2^2 \\ \cdot & \cdot & x_2x_3 \\ \cdot & x_3^2 & x_3^2 \end{bmatrix}$$

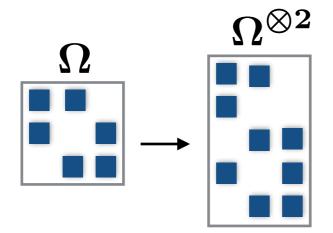
Impossible!

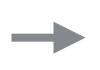
$$\begin{bmatrix} x_1^2 & x_1^2 & x_1^2 & & & \\ & x_1x_2 & x_1x_2 & & & \\ & & x_1x_3 & & & \\ x_2^2 & & & & & x_2^2 \\ & & & & & x_2x_3 & & x_2x_3 \\ & & & & & & x_3^2 \end{bmatrix}$$

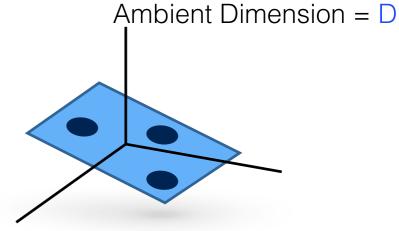
Small letters in LRMC: Incoherence and Uniform Sampling

In general

Subspace Dimension = R







Given: available samplings

Can we find §?

Theorem (P.-A., Ongie, Balzano, Willett, Nowak, 2017)

Suppose \mathcal{V} is in general position. With probability 1, S can be uniquely recovered if and only if there is a matrix $\Omega_{\star}^{\otimes 2}$ formed with D-R columns of $\Omega_{\star}^{\otimes 2}$ such that every $\Omega_{\ell}^{\otimes 2}$ formed with a subset of columns in $\Omega_{\star}^{\otimes 2}$ satisfies:

#rows_with_observations(
$$\Omega_{\ell}^{\otimes 2}$$
) \geq #columns($\Omega_{\ell}^{\otimes 2}$) + R.

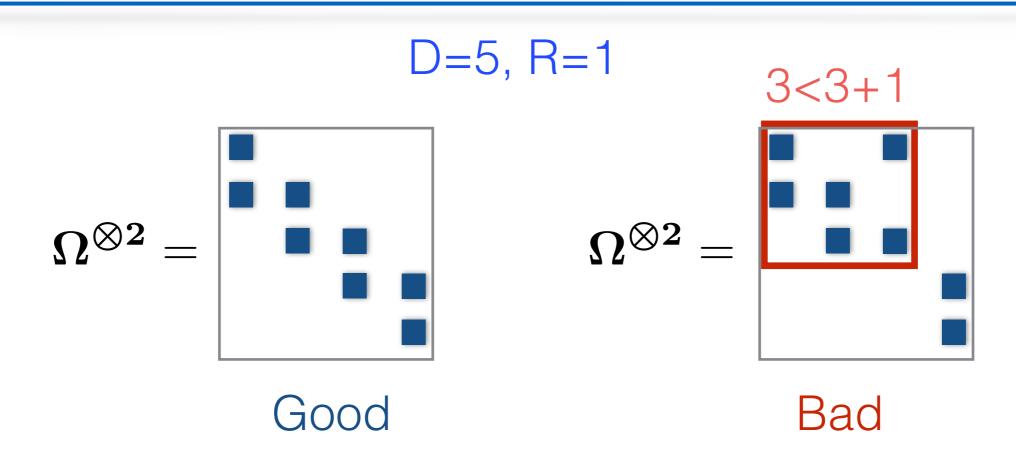
Furthermore, this condition is true if and only if $\dim \ker \mathbf{A}^{\mathsf{T}} = \mathsf{R}$, whence $S = \ker \mathbf{A}^{\mathsf{T}}$.

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$$\#rows_with_observations(\Omega_{\ell}^{\otimes 2}) \ge \#columns(\Omega_{\ell}^{\otimes 2}) + R.$$

Furthermore, this condition is true if and only if $\dim \ker \mathbf{A}^T = \mathbb{R}$, whence $S = \ker \mathbf{A}^T$.



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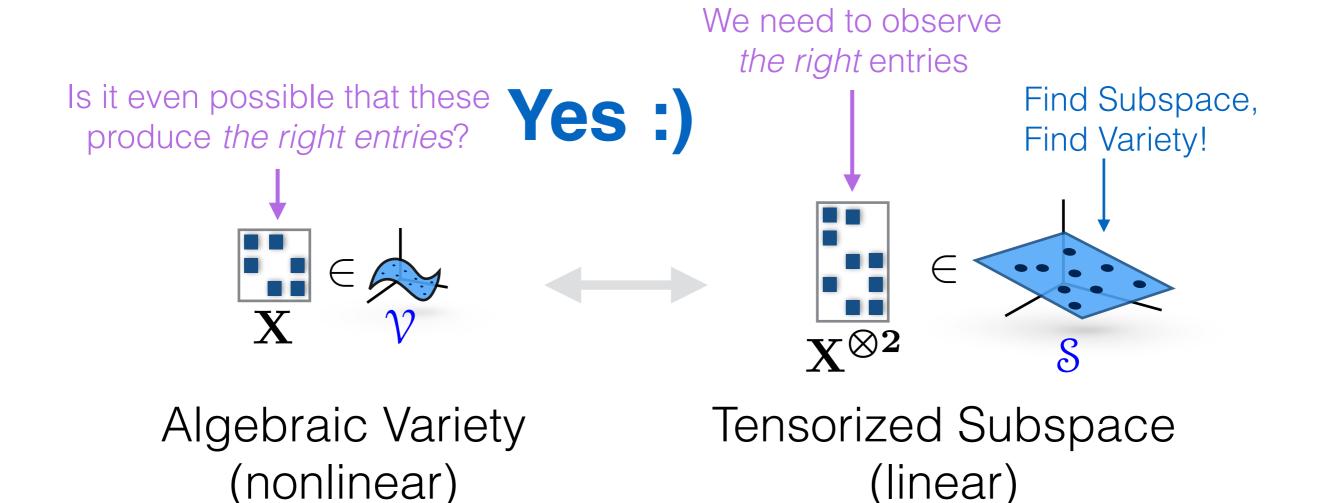
```
#rows_with_observations(\Omega_{\ell}^{\otimes 2}) \geq#columns(\Omega_{\ell}^{\otimes 2}) + R.
```

Furthermore, this condition is true if and only if $\dim \ker \mathbf{A}^T = \mathbb{R}$, whence $S = \ker \mathbf{A}^T$.

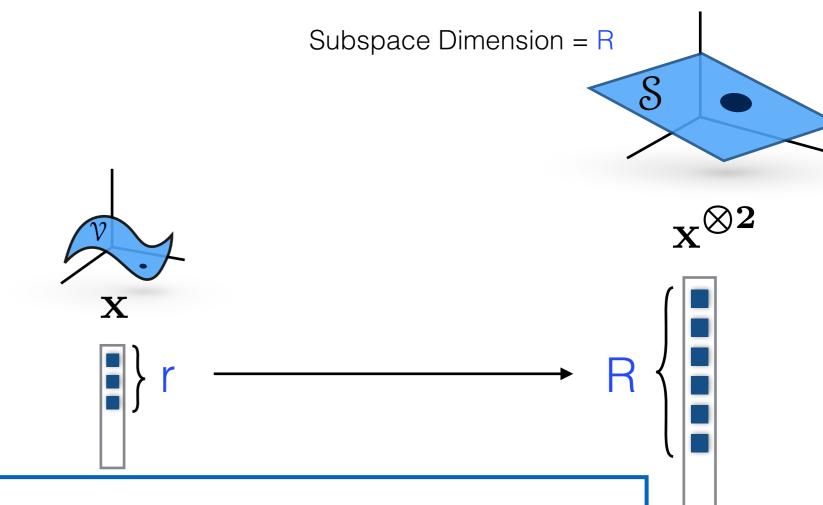
In words:

- Yes, it is possible to find the subspace S.
- Iff you observe the right entries (rows vs cols condition).
- There is an easy way to check this rows vs cols condition.
- If the condition is satisfied, there is an easy way to find δ .

So, what do we know so far?



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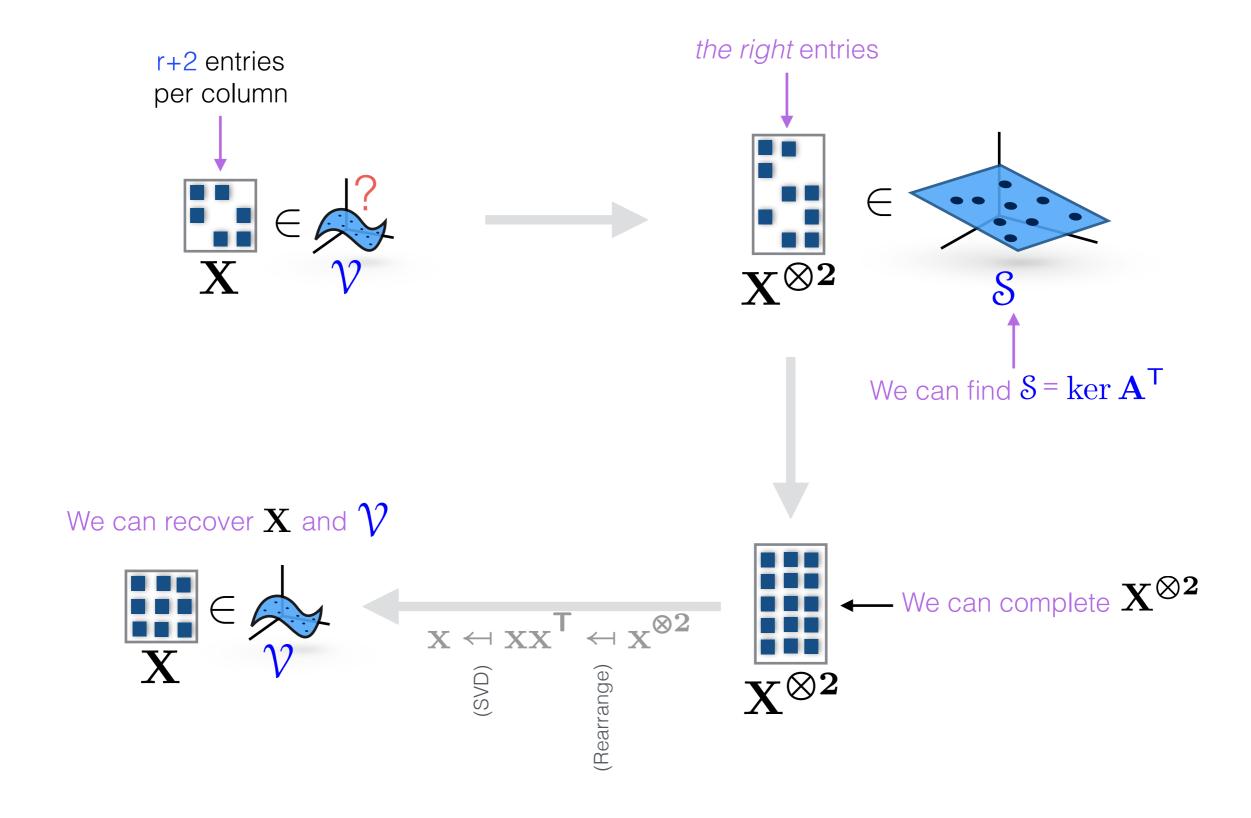


Theorem (P.-A., Ongie, Balzano, Willett, Nowak, 2017)

Suppose ${\mathcal V}$ is in general position. Suppose each column ${\mathbf x}$ has ${\mathsf m}$ samples.

- (i) If m < r, then S cannot be uniquely determined.
- (ii) There are cases with m = r and m = r+1 where S cannot be uniquely determined.
- (iii) If $m \ge r+2$, then S can be uniquely determined (if you observe the right entries).

So, what do we know so far?



So, what do we know so far? (Provable Algorithm)

Thank you!

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