

Deterministic Conditions for Subspace Identifiability from Incomplete Sampling

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SILO

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Robert Nowak and Nigel Boston

Outline

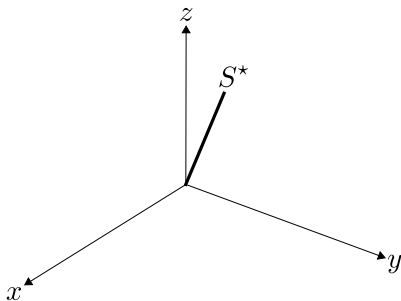
- ▶ Problem Description
- ▶ Setup
- ▶ The Answer
- ▶ Sketch of the proof
- ▶ Application
- ▶ Conclusions

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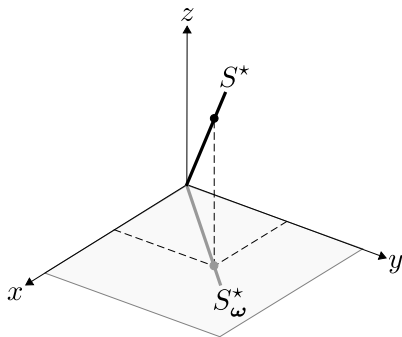
Problem description

S^* := r -dimensional subspace of \mathbb{R}^d , $r < d$.



Problem description

S_{ω}^* := Projection of S^* onto a canonical subspace.

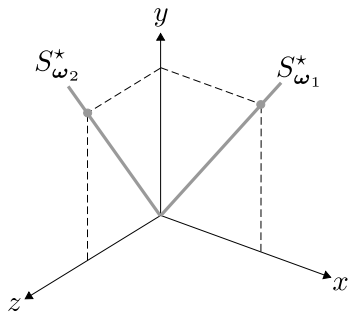


Problem description

Suppose I don't tell you S^* ...

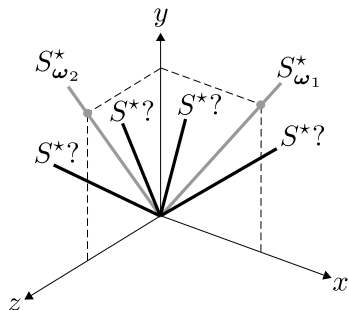
Problem description

Suppose I don't tell you S^* ... but I give you a set of projections of S^* onto some canonical subspaces.



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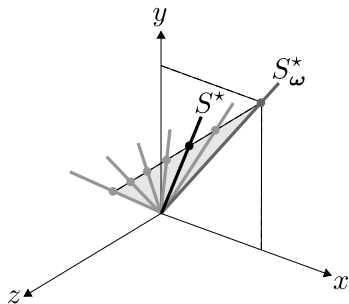


Can you uniquely determine S^* from this set of projections?

Problem description

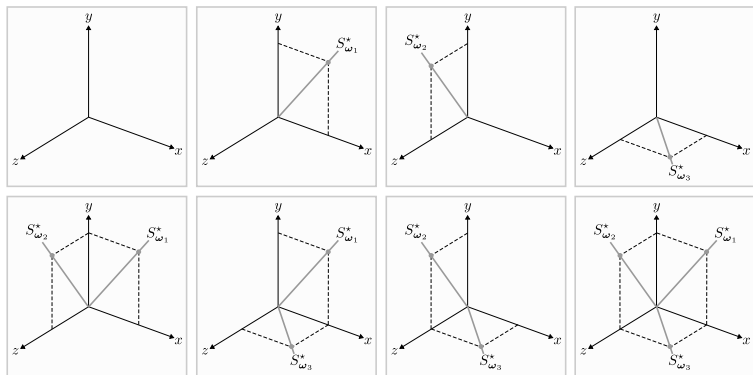
Is this even possible?

There might be many subspaces that agree with the projections.



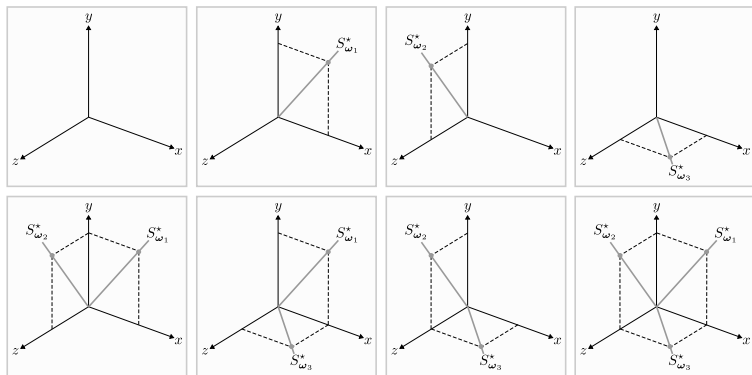
Problem description

Well... it depends on which set of projections I give you.



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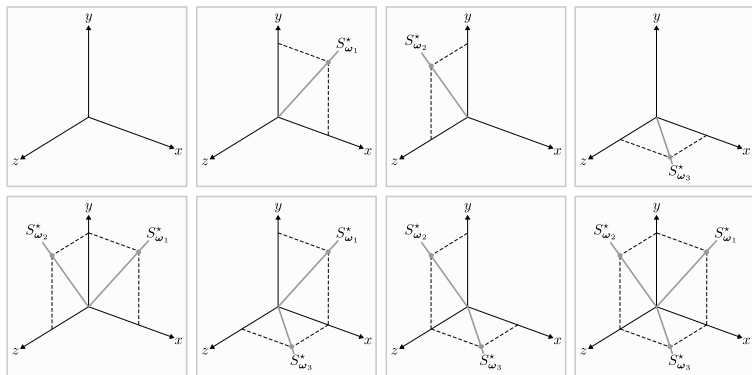
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Can you tell which are *the good sets*?

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Can you tell which are *the good sets*?

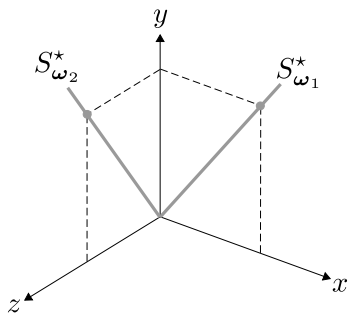
This is what we answer here: which are *the good sets*.

Outline

- ▶ Problem Description ✓
- ▶ **Setup**
- ▶ The Answer
- ▶ Sketch of the proof
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Setup

The columns of Ω will index the given projections.



$$\Omega = \begin{bmatrix} \omega_1 & \omega_2 \\ 1 & 0 \\ 1 & 1 \\ 0 & 1 \end{bmatrix}$$

Setup

In higher dimensions:

$$\Omega = \begin{array}{c} \omega_1 \quad \omega_2 \\ \left[\begin{array}{cc} 1 & 0 \\ 1 & 0 \\ 1 & 0 \\ 0 & 1 \\ 0 & 1 \\ 0 & 1 \end{array} \right] \end{array} \Rightarrow \left\{ \begin{array}{cc} \left[\begin{array}{cc} u_{11} & u_{12} \\ u_{21} & u_{22} \\ u_{31} & u_{32} \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{array} \right], & \left[\begin{array}{cc} 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ u_{41} & u_{42} \\ u_{51} & u_{52} \\ u_{61} & u_{62} \end{array} \right] \end{array} \right\}$$

Setup

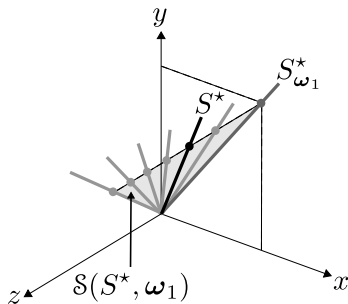
- ▶ $\text{Gr}(r, \mathbb{R}^d) :=$ Grassmannian manifold of r -dimensional subspaces in \mathbb{R}^d .

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- ▶ $\text{Gr}(r, \mathbb{R}^d) :=$ Grassmannian manifold of r -dimensional subspaces in \mathbb{R}^d .
- ▶ $\mathcal{S}(S^*, \Omega) :=$ Set of r -dimensional subspaces that agree with S^* on Ω .

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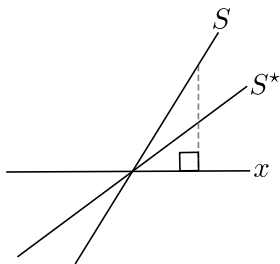


Setup

- ▶ S^* is r -dimensional.

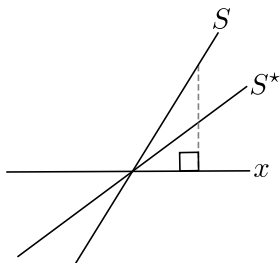
Setup

- ▶ S^* is r -dimensional.
- ▶ The projection of S^* onto $\leq r$ canonical coordinates gives no information about S^* .



Setup

- ▶ S^* is r -dimensional.
- ▶ The projection of S^* onto $\leq r$ canonical coordinates gives no information about S^* .



- ▶ \Rightarrow Assume w.l.o.g. that all projections are onto $r + 1$ canonical coordinates.

Setup

- ▶ For any matrix Ω' formed with a subset of the columns in Ω :

$$\Omega' = \underbrace{\begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}}_{n(\Omega') := \# \text{columns}} \left. \vphantom{\begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}} \right\} m(\Omega') := \# \text{nonzero rows}$$

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- ▶ $d - r$ projections are *necessary*, so we will assume w.l.o.g.

$$n(\Omega) = d - r.$$

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The Answer

Theorem (Pimentel-Alarcón, Nowak, Boston, '14)

For almost every S^ , with respect to the uniform measure over $\text{Gr}(r, \mathbb{R}^d)$, S^* is the only subspace in $\mathcal{S}(S^*, \Omega)$ if and only if for every matrix Ω' formed with a subset of the columns in Ω ,*

$$m(\Omega') \geq n(\Omega') + r.$$

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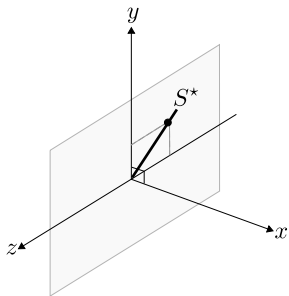
There is a set of measure zero of *bad* subspaces that we wouldn't identify.

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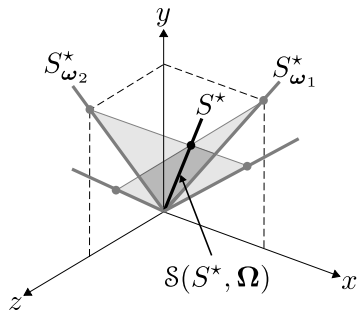
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This is what we want!



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Every subset of n columns of Ω has at least $n + r$ nonzero rows.

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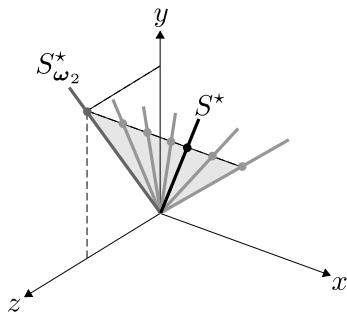
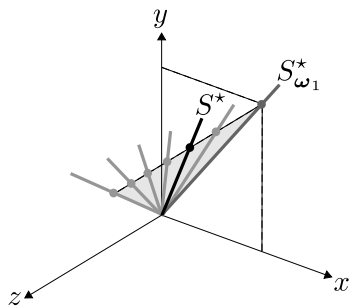
$$\Omega = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \Rightarrow \text{Check: } \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 & 1 \\ 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 1 \\ 1 & 0 \\ 0 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 1 \\ 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 1 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

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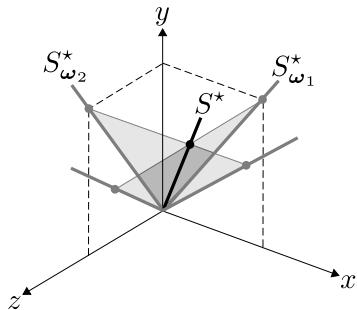
Sketch of the proof

We will find the subspaces that agree with *each* projection.



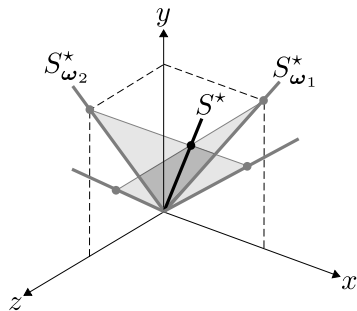
Sketch of the proof

Then find the intersection.



Sketch of the proof

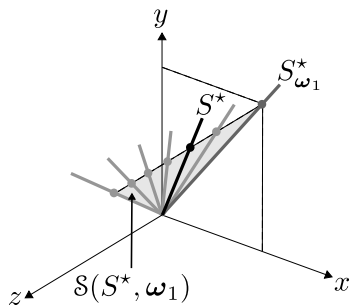
Then find the intersection.



If the intersection only contains one subspace, then ;)

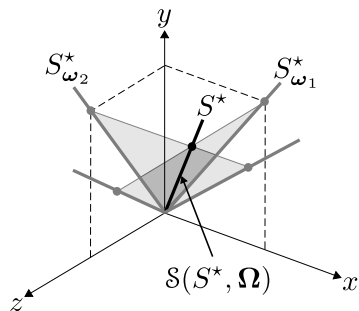
Sketch of the proof

$\mathcal{S}(S^*, \omega_i) :=$ Set of r -dimensional subspaces matching S^* on ω_i .



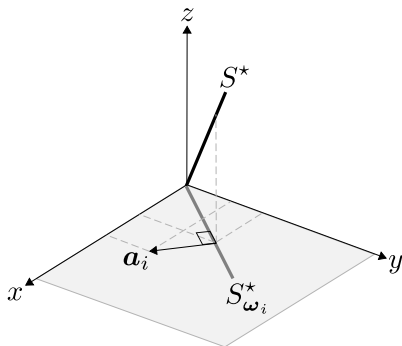
Sketch of the proof

$$\mathcal{S}(S^*, \Omega) = \bigcap_i \mathcal{S}(S^*, \omega_i).$$



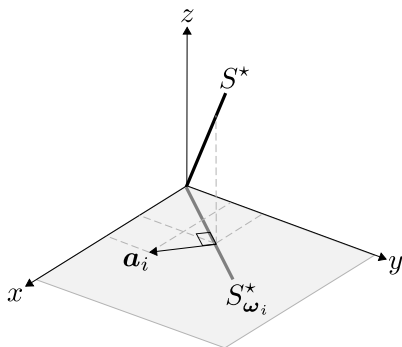
Sketch of the proof

$\mathbf{a}_i :=$ Vector orthogonal to the i^{th} projection.



Sketch of the proof

\mathbf{a}_i := Vector orthogonal to the i^{th} projection.



An entry in \mathbf{a}_i is zero iff the corresponding entry in ω_i is zero.

Sketch of the proof

One great thing:

- ▶ Every subspace in $\mathcal{S}(S^*, \omega_i)$ is orthogonal to \mathbf{a}_i .

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Cool! \Rightarrow

- ▶ Construct

$$\mathbf{A} = [\mathbf{a}_1 \mid \cdots \mid \mathbf{a}_N].$$

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One great thing:

- ▶ Every subspace in $\mathcal{S}(S^*, \omega_i)$ is orthogonal to \mathbf{a}_i .

Cool! \Rightarrow

- ▶ Construct

$$\mathbf{A} = [\mathbf{a}_1 \mid \cdots \mid \mathbf{a}_N].$$

- ▶ Every $S \in \mathcal{S}(S^*, \Omega)$ must be contained in

$$\ker \mathbf{A}^T.$$

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- ▶ If $\dim \ker \mathbf{A}^T > r$
⇒ There are many subspaces that agree with the projections
- ▶ If $\dim \ker \mathbf{A}^T = r$
⇒ Only S^* will agree with the projections. Moreover,

$$S^* = \ker \mathbf{A}^T$$

Sketch of the proof

- ▶ For any matrix \mathbf{A}' formed with a subset of the columns in \mathbf{A} :

$$\mathbf{A}' = \underbrace{\begin{bmatrix} a_{11} & 0 \\ a_{21} & a_{22} \\ 0 & a_{32} \\ 0 & 0 \end{bmatrix}}_{n(\mathbf{A}') := \# \text{columns}} \left. \vphantom{\begin{bmatrix} a_{11} & 0 \\ a_{21} & a_{22} \\ 0 & a_{32} \\ 0 & 0 \end{bmatrix}} \right\} m(\mathbf{A}') := \# \text{nonzero rows}$$

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- ▶ We want $\dim \ker \mathbf{A}^T = r$, so \mathbf{A} better have $d - r$ linearly independent columns.

Sketch of the proof

We know how to deal with \mathbf{A} using linear algebra!

- ▶ Through some technical details:

Lemma (Pimentel-Alarcón, Nowak, Boston, '14)

For almost every S^ , the columns of \mathbf{A} are linearly dependent if and only if $m(\mathbf{A}') < n(\mathbf{A}') + r$ for some matrix \mathbf{A}' formed with a subset of the columns in \mathbf{A} .*

Sketch of the proof

The zero entries of $\mathbf{\Omega}$ and \mathbf{A} are in the same positions.

$$\mathbf{\Omega} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \iff \mathbf{A}' = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & 0 & 0 \\ 0 & a_{32} & 0 \\ 0 & 0 & a_{43} \end{bmatrix}$$

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Then

$$m(\mathbf{\Omega}') \geq n(\mathbf{\Omega}') + r \iff m(\mathbf{A}') \geq n(\mathbf{A}') + r$$

□

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- ▶ Iff S^* is the only subspace in $\mathcal{S}(S^*, \Omega)$.



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Application

Low-Rank Matrix Completion (LRMC)

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- ▶ Given a subset of entries in a rank r matrix, exactly recover *all* of the missing entries.

$$\mathbf{x}_{\Omega} = \begin{bmatrix} 1 & \cdot & 3 & \cdot \\ 1 & 2 & \cdot & \cdot \\ \cdot & 2 & 3 & \cdot \\ \cdot & \cdot & \cdot & 4 \\ \cdot & \cdot & \cdot & 4 \end{bmatrix} \Rightarrow \hat{\mathbf{x}} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 1 & 2 & 3 & 4 \\ 1 & 2 & 3 & 4 \\ 1 & 2 & 3 & 4 \\ 1 & 2 & 3 & 4 \end{bmatrix}$$

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- ▶ \sim Identifying the subspace spanned by the columns, S^* .

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- ▶ \sim Identifying the subspace spanned by the columns, S^* . Here

$$\hat{S} = \text{span} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

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- ▶ Maybe the real completion is:

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And the real subspace is

$$S^* = \text{span} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 2 \\ 2 \end{bmatrix}$$

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How do we know we got the right completion (subspace)?
Known results e.g. (Candès and Recht, '09)

E. Candès and G. Recht (2009). Exact Matrix Completion Via Convex Optimization. In *Foundations of Computational Mathematics*, vol. 9, pp. 717–772.

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- ▶ Require random observed entries.
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- ▶ Require incoherence
 - ▶ Sufficient, but not necessary condition.
 - ▶ Generally unverifiable or unjustified in practice.
- ▶ Work with high probability (if assumptions are met).

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Application

How do we know we got the right completion (subspace)?

Known results e.g. (Candès and Recht, '09)

- ▶ Require random observed entries.
 - ▶ May not be justified.
- ▶ Require incoherence
 - ▶ Sufficient, but not necessary condition.
 - ▶ Generally unverifiable or unjustified in practice.
- ▶ Work with high probability (if assumptions are met).

What if these assumptions are not met? How can we validate a completion?

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Corollary (Pimentel-Alarcón, Nowak, Boston, '14)

Let the columns of \mathcal{X} be drawn independently according to μ , an absolutely continuous distribution with respect to the Lebesgue measure on S^ . Suppose \mathcal{X}_{Ω} can be partitioned into two sets of columns, \mathcal{X}_{Ω_1} and \mathcal{X}_{Ω_2} , such that Ω_2 satisfies the conditions of the subspace identifiability theorem.*

Let \hat{S} be the output of running an LRMC algorithm on \mathcal{X}_{Ω_1} . Then for almost every S^ , and almost surely with respect to μ , \mathcal{X}_{Ω_2} fits in \hat{S} if and only if $\hat{S} = S^*$.*

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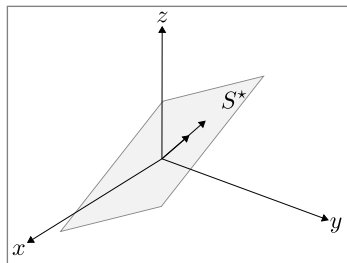
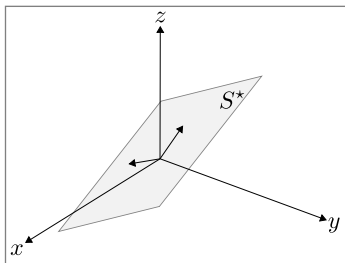
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- ▶ Hold with probability 1.

Outline

- ▶ Problem Description ✓
- ▶ Setup ✓
- ▶ The Answer ✓
- ▶ Sketch of the proof ✓
- ▶ Application ✓
- ▶ **Conclusions**

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- ▶ It is possible to uniquely identify an r -dimensional subspace S^* from its projections onto Ω .
- ▶ If and only if every subset of n columns of Ω has at least $n + r$ nonzero rows.
- ▶ Whence $S^* = \ker \mathbf{A}^T$.

Thanks.