CS 4780/6780: Fundamentals of Data Science

Spring 2019

## Topic 6: Linear Regression

INSTRUCTOR: DANIEL L. PIMENTEL-ALARCÓN

© Copyright 2019

## GO GREEN. AVOID PRINTING, OR PRINT DOUBLE-SIDED.

### 6.1 Introduction

One of the most elemental problems in data science can be summarized as predicting the value of a variable of interest y as a function of other variables  $x_1, \ldots, x_D$ . For example:

- Predicting my glucose level (variable of interest) as a function of my height, weight, age, and gender (other variables).
- Predicting stock prices (variable of interest) as a function of the market state (other variables).
- Predicting the activation level of a gene that determines a disease, like cancer (variable of interest) as a function of other genes' activation levels (other variables); this is often known as genomics wide association studies (GWAS).
- Predicting magnitude of solar flares (variable of interest) as a function of solar images (other variables).

The main idea behind linear regression is to write y as a linear combination of  $x_1, \ldots, x_D$ , i.e.

$$\mathbf{y} = \beta_0 + \beta_1 \mathbf{x}_1 + \beta_2 \mathbf{x}_2 + \dots + \beta_D \mathbf{x}_D, \tag{6.1}$$

where  $\beta_0$  is essentially an *offset*, and  $\beta_1, \beta_2, \ldots, \beta_D$  are the weights of each variable. For instance, in our glucose example, (6.1) is essentially saying:

glucose level =  $\beta_0 + \beta_1$ height +  $\beta_2$ weight +  $\beta_3$ age +  $\beta_4$ gender.

Notice that by letting  $\mathbf{x} = \begin{bmatrix} 1 & x_1 & x_2 & \cdots & x_D \end{bmatrix}^{\mathsf{T}}$  and  $\boldsymbol{\beta} = \begin{bmatrix} \beta_0 & \beta_1 & \beta_2 & \cdots & \beta_D \end{bmatrix}^{\mathsf{T}}$  we can rewrite (6.1) in vector form as

$$\mathbf{y} = \mathbf{x}^{\mathsf{T}} \boldsymbol{\beta}. \tag{6.2}$$

The goal is to determine the weights vector  $\beta$  that best explains y as a function of x.

# **6.2** Finding $\beta$

In order to find the coefficient vector  $\boldsymbol{\beta}$  that best explains y as a function of  $\mathbf{x}$  we use *training data*. The main idea is to observe *training pairs*  $\{\mathbf{x}_i, y_i\}_{i=1}^N$ , and find the vector  $\boldsymbol{\beta}$  such that  $y_i \approx \mathbf{x}_i^{\mathsf{T}} \boldsymbol{\beta}$  for every i = 1, ..., N.

More precisely, we want to find  $\beta$  such that

$$y_i = \mathbf{x}_i^{\mathsf{T}} \boldsymbol{\beta} + \epsilon_i$$
 for every  $i = 1, \dots, N$ ,

where  $\epsilon_i$  is a small error. Letting  $\mathbf{y} = [y_1 \ y_2 \ \cdots \ y_N]^T$ ,  $\mathbf{X}^T = [\mathbf{x}_1 \ \mathbf{x}_2 \ \cdots \ \mathbf{x}_N]$ , and  $\boldsymbol{\epsilon} = [\epsilon_1 \ \epsilon_2 \ \cdots \ \epsilon_N]^T$ , we can rewrite this in matrix form as:

$$\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon}. \tag{6.3}$$

Our goal can then be rephrased as finding the  $\beta$  that minimizes the size of  $\epsilon$ , or equivalently, the difference between **y** and **X** $\beta$ , i.e.,

$$\boldsymbol{\beta}^{\star} = \underset{\boldsymbol{\beta} \in \mathbb{R}^{D+1}}{\operatorname{arg\,min}} \| \mathbf{y} - \mathbf{X} \boldsymbol{\beta} \|_{2}^{2}.$$
(6.4)

Recall that

$$\|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|_2^2 = \sum_{i=1}^N (y_i - \mathbf{x}_i^\mathsf{T}\boldsymbol{\beta})^2,$$

so (6.4) is minimizing the squared error of the entire sample. Intuitively,  $\beta^{\star}$  is the *line* that best explains the y<sub>i</sub>'s as function of the  $\mathbf{x}_i$ 's. This is illustrated in the following figure, where each point represents a pair  $(\mathbf{x}_i, y_i)$ :



#### **6.2.1** Solving (6.4)

In order to solve (6.4), notice that:

$$\|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|_{2}^{2} = (\mathbf{y} - \mathbf{X}\boldsymbol{\beta})^{\mathsf{T}}(\mathbf{y} - \mathbf{X}\boldsymbol{\beta})$$
$$= \mathbf{y}^{\mathsf{T}}\mathbf{y} - \mathbf{y}^{\mathsf{T}}\mathbf{X}\boldsymbol{\beta} - \boldsymbol{\beta}^{\mathsf{T}}\mathbf{X}^{\mathsf{T}}\mathbf{y} + \boldsymbol{\beta}^{\mathsf{T}}\mathbf{X}^{\mathsf{T}}\mathbf{X}\boldsymbol{\beta}$$
$$= \mathbf{y}^{\mathsf{T}}\mathbf{y} - 2\boldsymbol{\beta}^{\mathsf{T}}\mathbf{X}^{\mathsf{T}}\mathbf{y} + \boldsymbol{\beta}^{\mathsf{T}}\mathbf{X}^{\mathsf{T}}\mathbf{X}\boldsymbol{\beta}.$$

At this point we can take the derivative with respect to  $\beta$ . Notice that  $\beta$  is a vector, so taking derivative is a bit tricky. To learn more about how to take derivatives w.r.t. vectors and matrices see *Old and new matrix algebra useful for statistics* by Thomas P. Minka. Using the tricks therein, we know that the derivative w.r.t.  $\beta$  is:

$$2\mathbf{X}^{\mathsf{T}}\mathbf{X}\boldsymbol{\beta} - 2\mathbf{X}^{\mathsf{T}}\mathbf{y}$$

Setting this to zero and solving for  $\beta$ , we have that

$$\boldsymbol{\beta}^{\star} = (\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\mathbf{y}$$

which is tightly related to the projector operator onto  $\operatorname{span}{\mathbf{X}}$ .

# **6.3** We've found $\beta^*$ . Then what?

Recall that our ultimate goal is to predict y as a function of **x**. To this end, linear regression aims to find the *line* that explains each  $y_i$  as a function its corresponding  $\mathbf{x}_i$ . Such *line* is determined by  $\boldsymbol{\beta}$ . Given  $\mathbf{x}_i$ , the linear prediction of  $y_i$  is given by  $\mathbf{x}_i^T \boldsymbol{\beta}$ , and  $\epsilon_i$  is the *error* between the prediction  $\mathbf{x}_i^T \boldsymbol{\beta}$  and the truth,  $y_i$ :



Once we have found  $\beta^*$ , we have found the line that *best* explains each  $y_i$  in our training data as a function of its corresponding  $\mathbf{x}_i$ . Substituting  $\beta^*$ , we see that the best linear prediction of each  $y_i$  is given by  $\mathbf{x}_i^{\mathsf{T}} \beta^* = \mathbf{x}_i^{\mathsf{T}} (\mathbf{X}^{\mathsf{T}} \mathbf{X})^{-1} \mathbf{X}^{\mathsf{T}} \mathbf{y}$ . Extrapolating this, given a new vector  $\mathbf{x}$  (for which we do not know y), we can predict its y as  $\mathbf{x}^{\mathsf{T}} \beta^* = \mathbf{x}^{\mathsf{T}} (\mathbf{X}^{\mathsf{T}} \mathbf{X})^{-1} \mathbf{X}^{\mathsf{T}} \mathbf{y}$ :



### 6.4 A Top to Bottom Example

Scientists have discovered a new deadly disease with 90% mortality rate. However, if detected in time, people can take preventive measures to reduce mortality rate to only 5%. The problem is that the test to determine

a person's risk to develop this new disease is extremely expensive. To overcome this problem, you decide to run an experiment. You will test N people, and record their results in a data vector  $\mathbf{y}$ . In addition you will store other D indicators about these N people (such as height, weight, and gender) in a data matrix  $\mathbf{X}$ . Using this information you will try to find a coefficient vector  $\boldsymbol{\beta}$  that best explains  $\mathbf{y}$  as a function of  $\mathbf{X}$ . In words, you will try to predict a person's risk of developing the disease as a function of their other indicators.

Since you took CS 4780/6780, you know that the best  $\beta$  is given by  $\beta^* = (\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\mathbf{y}$ . Using this information, you are now able to predict the chance that *every* person in the world develops the disease as follows. For each person whose risk is unknown, collect the D indicators in a vector  $\mathbf{x}$  (which can be easily and cheaply done), and compute her risk as  $\mathbf{x}^{\mathsf{T}}(\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\mathbf{y}$ .

This is precisely the approach that is currently done in genomic wide association studies (GWAS) to predict a person's risk to develop cancer and other diseases, where the D indicators include people's genome, in addition to their demographics.